The ABC of EMG

A Practical Introduction
to Kinesiological Electromyography

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Version 1.4 March 2006
Fig. 1: A fundamental EMG textbook. Basmajian & De Luca: *Muscles Alive* (2)
Electromyography...

“..is the study of muscle function through the inquiry of the electrical signal the muscles emanate.”
Medical Research
- Orthopedic
- Surgery
- Functional Neurology
- Gait & Posture Analysis

Rehabilitation
- Post surgery/accident
- Neurological Rehabilitation
- Physical Therapy
- Active Training Therapy

Ergonomics
- Analysis of demand
- Risk Prevention
- Ergonomics Design
- Product Certification

Sports Science
- Biomechanics
- Movement Analysis
- Athletes Strength Training
- Sports Rehabilitation
Fig. 4: Direct look into the body / muscle function: EMG synchronized with video and other movement sensors. Software screenshot of MyoResearch XP™ - NORAXON INC. USA
Fig. 5: Motor unit. Adopted & modified from 2,7.
Fig. 6: Schematic illustration of depolarization / repolarization cycle within excitable membranes.
Fig. 7: The Action Potential. Adopted & redrawn from 5, p. 164
Fig. 8: The depolarization zone on muscle fiber membranes. Adopted & modified from [7 & 73].
Fig. 9: The model of a wandering electrical dipole on muscle fiber membranes. Adopted & modified from 7, p. 73
Fig. 10: Generation of the triphasic motor unit action potential. Adopted & modified from 2, p. 68
25 mathematically generated MUAPs

Superposed signal

Fig. 11: Superposition of MUAPs to a resulting electromyogram. Adopted & modified from 2, p. 81
Fig. 12: Recruitment and firing frequency of motor units modulates force output and is reflected in the superposed EMG signal. Adopted & modified from [7, p. 75]
Fig. 13: The raw EMG recording of 3 contractions bursts of the M. biceps br.
Fig. 14: The influence of varying thickness of tissue layers below the electrodes: Given the same amount of muscle electricity, condition 1 produces more EMG magnitude due to smaller distance between muscle and electrodes.
Fig. 15: Raw EMG recording with heavy ECG interference
Fig. 16: Electrode leads with cable built-in pre-amplifiers System NORAXON INC USA
Fig. 16: Electrode leads with cable built-in pre-amplifiers System NORAXON INC USA
Fig. 17: Variety of EMG amplifiers ranging from 1 or 2 channel Biofeedback units to tethered and telemetric systems. Systems by NORAXON INC. USA
Fig. 18: The effect of A/D sampling frequency on a digitized signal. Too low frequencies (lower traces) result in significant loss of signal information.
Fig. 19: Selection of special EMG electrodes (1, 2 NORAXON INC. USA) and regular ECG electrodes (3, 4 AMBU-Blue Sensor)
Fig. 21: Schematics of a fine wire electrode: two fine wires with un-isolated endings are located with a steel cannula. System MEDELEC.
Fig. 22: Procedure to insert the fine wires into the muscle tissue. After removing the needle, the distal endings of the wires are connected to steel spring adapters, which again are connected to the regular EMG pre-amplifier lead.
Fig. 22: Raw fine wire EMG recording of the M. tibialis posterior (upper blue trace) in treadmill walking. Baseline shifts indicate motion artifacts. The baseline can be stabilized by applying a 20 Hz highpass filter (lower red curve) – Institut fuer Biomechanik & Orthopaedie, D. Sporthochschule Köln-Germany)
Fig. 23: Anatomical landmarks on the human body in dorsal and frontal view.

- C7 proc. spinosus
- Acromion
- Scapula trionum spinae
- TH 3 proc. spinosus
- Medial border of scapula
- Scapula angularis inferior
- TH 8 proc. spinosus
- Epicondylus lateralis / medialis
- Olecranon
- L1/2.5 proc. spinosus
- Spina iliaca superior
- Processus styloideus ulnae
- Processus styloideus radii
- Trochanter major
- Epicondylus lateralis / medialis
- Heel / calcaneum
- Acromion
- Medial clavicular head
- Sternum
- Fossa cubitalis
- Rib cage
- Umbilicus
- Crista iliaca
- Spina iliaca anterior superior
- Circumference Point
- Patella
- Knee joint
- Head of Fibula
- Circumference Point
- Tibia bone
- Malleolus medialis / lateralis
Fig. 24: Migration of the muscle belly below the electrode pair attached at the biceps brachii. Note the in the extended position (right picture) the distal electrode has left the active muscle area. It is needed to attach electrodes at center position in the most flexed position.
Fig. 25: Cable secured with elastic straps and tape
Fig. 26b: Anatomical positions of selected electrode sites, dorsal view. The left side indicates deep muscles and positions for fine wire electrodes, while the right side is for surface muscles and electrodes.
Fig. 27: EMG electrode impedance tester – model NORAXON INC. USA
<table>
<thead>
<tr>
<th>Impedance range (KOhm)</th>
<th>Recommendation</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 - 5</td>
<td>- very good condition</td>
</tr>
<tr>
<td>5 - 10</td>
<td>- good and recommended if feasible</td>
</tr>
<tr>
<td>10 - 30</td>
<td>- acceptable for easy conditions</td>
</tr>
<tr>
<td>30 - 50</td>
<td>- less good, attention is needed (see next chapter)</td>
</tr>
<tr>
<td>&gt; 50</td>
<td>- should be avoided or requires a second cleaning run</td>
</tr>
</tbody>
</table>

*Fig. 28: Recommendations for electrode/skin impedance ranges*
Fig. 29: Visual (left) and numerical (right) evaluation of the EMG baseline quality. The left raw EMG trace shows an example for a nearly perfect EMG recording with stable flat EMG baseline between active contractions. A quick analysis of a baseline section (blue area) indicates a mean noise level of 1.8 microvolts. System NORAXON INC. USA.
Fig. 30: Example for an offset shifted baseline. Special post recording edit functions should be applied to correct the shift.
Fig. 31: The total power spectrum of a surface EMG recording: most of the signal power is located between 10 and 250 Hz.
Fig. 33: EMG raw recording contaminated by power hum noise
Fig. 34: EMG raw recording with offset shift positive side
Fig. 35: EMG raw recording with cable movement artifacts
Fig. 36: EMG raw recording with ECG spikes
Fig. 37: EMG raw recording (upper trace) and rectified EMG recording (same signal, lower trace)
Fig. 38: Comparison of two smoothing algorithms using the same window width: Being very similar in shape, the RMS algorithm (lower trace) shows higher EMG amplitude data than the MovAg (upper trace).
Fig. 39: Comparison of three smoothing algorithms and their effect on amplitude shape and statistics. The 6 Hz Butterworth Low Pass filter (lowest channel) compares to a Moving Average with 100ms window width. Both show the same shape and identical amplitude parameters.
Fig. 40: The concept of MVC normalization. Prior to the test/exercises a static MVC contraction is performed for each muscle. This MVC innervation level serves as reference level (=100%) for all future trials.
Fig. 41: MVC test sequence for trunk/hip flexor muscles (Rect. Abd., Obliquus ext. Abd., Rect. Femoris). The numbers below each test exercise indicate how many of 10 subjects showed highest innervation at that exercise.
Fig. 42: Example for an 8 channel MVC test sequence. Each MVC – test is repeated at least one time, interrupted by a pausing (red lines). An automatic algorithm detects the highest EMG portions (green bars labelled “MVC”) and stores them for further use. System MYORESEARCH XP, NORAXON INC. USA
### MVC Positions for forearm / shoulder muscles

<table>
<thead>
<tr>
<th>Muscle group</th>
<th>Exercise</th>
<th>Comments</th>
</tr>
</thead>
<tbody>
<tr>
<td>Forearm flexors / extensors</td>
<td><img src="image1.png" alt="Image" /></td>
<td>Select a seated or kneeling position (in front of a bench) and arrange a stable forearm support. Manual resistance, barbells or cable/belts can be used. Consider using the latissimus d. and pectoralis major MVC test as a control exercise.</td>
</tr>
<tr>
<td>Biceps Brachii</td>
<td><img src="image2.png" alt="Image" /></td>
<td>A valid biceps MVC needs to be fastened securely at the elbow and trunk. The best arrangement is in a seated or kneeling position (in front of a bench). Consider using the latissimus d. MVC-test as a control exercise.</td>
</tr>
<tr>
<td>Triceps Brachii</td>
<td><img src="image3.png" alt="Image" /></td>
<td>Some instruction as biceps b! Consider using the pectoralis major MVC-test as a control exercise.</td>
</tr>
<tr>
<td>Deltoides</td>
<td><img src="image4.png" alt="Image" /></td>
<td>Select a seated position, if possible with the back in a fixed position. Fasten the straps near the arms close to the 90° position. The bilateral contractions guarantee a balanced force distribution for the trunk. The abduction works best for the pars acromialis of the deltoid muscle. Consider a flexion/extension position for the pars clavicularis.</td>
</tr>
<tr>
<td>Trapezius p. descendens</td>
<td><img src="image5.png" alt="Image" /></td>
<td>The MVC test can be performed with one side only. A static resistance can be arranged by manually restraining the arm or by arranging a large enough load to press the shoulder down (difficult).</td>
</tr>
<tr>
<td>Pectoralis major</td>
<td><img src="image6.png" alt="Image" /></td>
<td>Numerous test positions can be used! However, all of them need a very good shoulder/back resistance. The prone lying position would best be performed with a (fixed) long bar. The push up may work as an easy to set up alternative. Both positions should be performed in 90° elbow position.</td>
</tr>
<tr>
<td>Infraspinatus</td>
<td><img src="image7.png" alt="Image" /></td>
<td>Being the most important outward rotator of the shoulder cuff, any related outward rotation may work. Good results are achieved with uni- or bilateral manual resistance against the forearm.</td>
</tr>
<tr>
<td>Trapezius p. trans. / Rhomboideus</td>
<td><img src="image8.png" alt="Image" /></td>
<td>The horizontal abduction best addresses the shoulder stabilization muscles. In the prone laying position a barbell or bilateral manual resistance can be used. The seated position requires the chest to be securely fastened and a cable or machine resistance (rowing machines).</td>
</tr>
<tr>
<td>Latissimus/Trapezius p. ascendance</td>
<td><img src="image9.png" alt="Image" /></td>
<td>The simulation of a pull-up produces the highest latissimus innervation. Consider/check a frontal and a lateral arm position at 90° elbow flexion. You may find MVCs for the biceps and the lower trapezius also.</td>
</tr>
</tbody>
</table>

**Fig. 43a:** Proposals for upper body MVC test arrangements. The black thin arrow indicates movement direction, the white thick arrow the resistance direction.
<table>
<thead>
<tr>
<th>Muscle group</th>
<th>Exercise</th>
<th>Comments</th>
</tr>
</thead>
<tbody>
<tr>
<td>Rectus abdominis / Obligus internus abdominis</td>
<td><img src="image1" alt="Image" /></td>
<td>A valid MVC test for the abdominals is difficult to arrange. Sit-up styled movements with the legs securely fastened work the best. Let the spine flex by around 30° and use a belt or manual restraint for that position. The obliques may fire more when an additional trunk rotation is added to the flexion.</td>
</tr>
<tr>
<td>Obligus extemus abdominis</td>
<td><img src="image2" alt="Image" /></td>
<td>This MVC test requires good coordinative skill. A side lying position with the leg and hip restrained is a good start position. Let the subject flex up and remain fixed early in the flexion position. An important check exercise is the MVC test for the rectus abdominis.</td>
</tr>
<tr>
<td>Erector spinae / Multididi</td>
<td><img src="image3" alt="Image" /></td>
<td>The prone lying position on a bench is a very productive MVC test position because all back muscles are facilitated within a muscle chain. MVCs for the erector spinae, the gluteus and the hamstrings are found here. A check exercise is the isolated back extension at a machine.</td>
</tr>
<tr>
<td>Glutaeus maximus</td>
<td><img src="image4" alt="Image" /></td>
<td>A control exercise for the glutaeus maximus muscle. It should be performed both in extended and flexed knee position with slightly outward rotated legs. The hyperextension position (~20°) is important.</td>
</tr>
<tr>
<td>Glutaeus medius</td>
<td><img src="image5" alt="Image" /></td>
<td>The hip abduction can be performed in fixed side lying position or supine position. Some subjects show higher EMGs in standing position.</td>
</tr>
<tr>
<td>Mm. adductores</td>
<td><img src="image6" alt="Image" /></td>
<td>A stiff and large roll cushion is pressed between the flexed legs.</td>
</tr>
<tr>
<td>Rectus femoris</td>
<td><img src="image7" alt="Image" /></td>
<td>An easy and beneficial exercise for all quadriceps muscles is a single leg knee extension between 90 and 70° knee flexion position.</td>
</tr>
<tr>
<td>Mm ischiocrurales</td>
<td><img src="image8" alt="Image" /></td>
<td>Isolated test for the hamstrings. Fasten the hip securely (bighalf person) and perform a unilateral knee flexion at ~20-30° knee flexion. An important check exercise is the prone lying MVC test for the erector spinae.</td>
</tr>
<tr>
<td>Gastrocnemius</td>
<td><img src="image9" alt="Image" /></td>
<td>Being one of the strongest human muscles, the trunk's suite group requires a very rigid (machine) resistance against the restrained hip. Perform an unilateral plantar flexion at 30° ankle position.</td>
</tr>
<tr>
<td>Soleus</td>
<td><img src="image10" alt="Image" /></td>
<td>This is an important check exercise for the soleus muscul because the gastrocnemius is at a difficult work position. Perform an unilateral plantar flexion. The knee needs to be strapped down in a rigid position due to large forces.</td>
</tr>
<tr>
<td>Tibialis anterior</td>
<td><img src="image11" alt="Image" /></td>
<td>The tibialis anterior usually can be restrained by manual resistance, work unilateral.</td>
</tr>
</tbody>
</table>

*Fig. 4.3b: Proposals for trunk, hip and leg MVC test arrangements. The black thin arrow indicates movement direction, the white thick arrows the resistance direction.*
Fig. 44: Amplitude normalization to the test internal mean (left) or peak value (right) of the averaged curve.
Fig. 45: Comparison of microvolt vs. mean value normalized ensemble averages of the medial gastrocnemius. The shape of the curve is not altered, but the variance (CV-coefficient of variance) is reduced due to mean normalization (left). Redrawn from 11, p. 64.
Fig. 46: Example of ECG affected EMG recording (upper trace) and the resulting signal after applying an ECG-reduction algorithm (lower trace). On the right side the FFT power spectrum of the interval between the two marks is shown. Note that both the EMG amplitude and the spectrum are not altered by the ECG reduction. System MyoResearch XP™, NORAXON INC USA
Fig. 47: Calculation errors produced by ECG interference on EMG traces near the rest line (relaxation studies). The amplitude mean value (MEAN) increases from 3.2 (cleaned) to 10.8 microvolt.
Fig. 48: Variability of single EMG patterns. Left side shows a signal superposition of 3 repetitions for three knee extensors (vastus medialis, lateralis, rectus femoris) for a free squat movement. A considerable EMG variance between repetitions is visible.

On the right side, a signal superposition (3 repetitions) of the vastus medialis EMG (upper trace) and the resulting torque output curve (lower trace) is shown for a concentric/eccentric knee extension/flexion using an isokinetics device. The EMG variability is reduced—mainly due to the single joint character of the knee extension in seated position.
Fig. 49: The concept of time normalization for repetitions/interval of different duration. Each repetition is segmented in a certain amount of equal portions and the mean value of each portion is used for the averaging.
Repetitive Movement Cycles in ms $\Rightarrow$

Time normalized cycle

Fig. 50: Generation of an averaged curve within a time normalized frame ranging from 0 to 100%
Fig. 51: Example of averaged curves, based on a isokinetic knee extension / flexion sequence at 60°/sec. Red = EMG, green = torque
Fig. 52: Comparisons of average EMG curves within the unique time format resulting from time normalization. EMG Pattern difference can easily be detected, qualitatively described and quantitatively be calculated if the same muscle is investigated in two different test conditions. If muscles (=different detection conditions!) are compared, the quantitative comparison should be avoided and the focus is set to the "innervation behaviour".
Fig. 53: Averaging without time normalization. A fixed interval before and/or after (blue activity section) a reproducible movement event (ground contact) is used as a standardized format for averaging. For the drop jump on a force plate, as shown above, a fixed interval of 100 ms is selected to describe the pre-innervation phase (yellow activity section), a 400 ms interval after the ground contact is used to describe the EMG activity (red curves) and impulse (green curves) of the jump.
Fig. 54: EMG standard amplitude parameters based on the rectified EMG curve.
Fig. 55: The Mean value of an analysis interval is calculated for three muscles. All values are summed and defined as 100%. The Input% calculates the percentage amount each muscle contributed.
Fig. 56: Model of frequency related signal decomposition based on FFT. The signal on left side contains 3 underlying waves (middle): a sinus wave at 1 Hz, another at 3 Hz and finally one wave at 5 Hz. The power distribution (right) indicates Power of different magnitudes at these frequencies. Adopted & redrawn from 3, p. 24.
Fig. 57: EMG standard frequency parameters based on FFT calculations
Fig. 58: Time to Peak calculation for an average curve. The beginning of the calculation period is the beginning of the movement cycle; the (time normalized) peak time point is an important parameter to describe average...
Fig. 59: Illustration of the Onset and Offset time period. Based on the beginning of an analysis period, a threshold criteria is applied to determine the Onset time of EMG. If the same threshold is passed again, the Offset time is reached.
Fig. 60: Adjustment of the SD multiplication factor to determine a reliable threshold level for EMG onsets/offsets. The threshold on left side is set to 3 standard deviations and fails to detect a valid activation (marker lines and pink bars). The noise free baseline requires an increase to 8 times SD to detect the contraction onset/offset correctly.
Fig. 61: Two classical static EMG/force experiments: The left figure (adopted & redrawn from 10, p. 110) shows the dependency of the EMG/force ratio from angle position (A,B), which can be eliminated by normalization of the MVC of force. The right figure (redrawn from 2, p. 193) shows EMG/force ratios of 3 different muscles for MVC normalized EMG and force output data.
Fig. 62: Schematic EMG/force relationship in ramp contractions. Depending on the muscle condition and training status, the ratio can change. Trained muscles need less EMG for a given force output than atrophic or fatigued muscles.
EMG in Biomechanics

- **Anthropometry**
  - “Body”
  - Bone & Segments - structure - proportion

- **Kinetematics**
  - “Movement”
  - Distance Angle Velocity & Accel.

- **Kinetics/Dynamometry**
  - “Forces”
  - Linear Force Moment/Torque Pressure distr.

- **Electromyography**
  - “Muscle Activation”
  - Muscle Action Potentials

**Kinesiological Analysis**
- Data Integration & Correlation

Fig. 63: The 4 major areas of biomechanical measurement methods. Based on Ballreich/Baumann 1983
Fig. 64: Analytical questions are the basis of proper sensor selection within biomechanical methods.
Fig. 65: Biological sub-systems that act in dependency to each other. A single finding within a selected subsystem does not reflect the whole system.
Fig. 66: EMG on/off-analysis of a regular upright standing / posture task. The multifidii (ch. 1) and internal obliques (ch. 4) show significant EMG activity (=on), whereas the glutaeus maximus (ch. 3) and rectus abdominis (ch. 4) are “off”. The same finding is found on instable ground or one leg standing – indicating which muscles really contribute to postural stability.
Fig. 67: The flexion-relaxation phenomenon. When slowly bending forward from an upright position, the back muscles (ch. 1 multifidii) and hip extensors (ch. 2 gluteus maximus) turn off at the most flexed position (dashed vertical line and video picture). The limb momentum is held by passive structures like ligaments. When slowly extending back, both muscles start firing again. Other synergists (ch. 3 hamstrings) may be active all the time. Low back pain patients can lack this innervation silence due to dysfunction or pain.
Fig. 68: Video-based EMG analysis of 4 different work activities (yellow intervals) measured in microvolts. Where is more or less EMG?
Fig. 69: EMG analysis of 5 abdominal exercises, ranked by the highest EMG found (basket hang) and scaled in arbitrary units. Data taken and rearranged from Gutin & Lopez, 1971
Fig. 70: Qualitative EMG analysis of the tibialis anterior (upper trace) and gastrocnemius medialis (lower trace) in left/right comparison of a spastic patient performing 3 squats. The more/less analysis focuses on side comparison and constancy between repetitions.
Fig. 71: On/Off timing pattern of ten lower leg muscles within a gait cycle. Blue bars indicate when the muscle is active. Adopted and modified from 8.
Fig. 72: EMG onset analysis on a tilting platform. The reflex induced onset of ankle stabilizers at unexpected tilt (dashed line) is calculated. Adapted and redrawn from Rosenbaum et al. 2000
Fig. 73: Delayed innervation (narrow dash line) of lumbar segmental stabilizers (Transversus abdominis, Multifidus) in ratio to the onset of the deltoid muscle (wide dash line) in rapid shoulder flexion done by a low back pain patient. Adapted & redrawn from 9, p. 62
Fig. 74: Muscular innervation profile of 8 hip/leg muscles in the horizontal squat movement. Data shows the MVC normalized mean EMG of 6 extension and flexion periods measured for a group of 10 subjects at 40% of the individual for one repetition maximum.
Fig. 75: EMG efficiency analysis for 3 different seat positions based on the MVC-normalized average curve of the multifidus muscle in a sequence of back flexion/extension cycles. At a given load (60% Max.), seat position 3 shows the highest EMG innervation.
Fig. 76: Ergonomic EMG analysis of two shoulder muscles (upper trace - trapezius p. desc; lower trace - deltoideus anterior) in a work task in a steel production process. The MVC normalized signal shows the muscular demand in ratio to the given video picture.
Fig. 77: Schematic illustration of the frequency shift towards lower frequencies in sustained contractions and calculation of the muscle fatigue index. Adopted and redrawn from De Luca.
Fig. 78: Typical test arrangement and findings for static back endurance tests: Median (A), Mean Frequency (B), Zero Crossing (C) and Mean Amplitude (D), slope of a trained (green) and untrained (blue) subject, measured for the multifidus muscle.
Fig. 79: Coordinative EMG analysis based on MVC normalized average curves (N=10, top rowers) over a sequence of 8 rowing cycles. The pattern analysis allows a precise description on how much and when a certain muscles fires within the investigated movement.
Fig. 80: Two clinical examples based on microvolt scaled RMS EMG analysis of muscle groups at video picture position. The left picture indicates EMG imbalance between the vasti within a knee stabilization task. The right pictures proves the appropriate innervation of lumbar stabilizers (multifidus, internal obliques) within a shoulder training exercise at a cable machine.
Fig. 81: Left/Right comparison of average curves (left side=black/injured) of 4 knee muscles within a free squat movement sequence (6 reps) of a patient 4 weeks after ACL- rupture and surgery. Due to mechanical knee instability, the flexors (ch. 8 hamstrings) act like agonists (black curve). Typically, minor innervation (red curve) is visible for this muscle group/exercise.
## Factor that influence a test exercise

<table>
<thead>
<tr>
<th>Factor</th>
<th>Comments</th>
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<tbody>
<tr>
<td><strong>Angle position</strong></td>
<td>The angle and muscle length directly influences the EMG amplitude because the active muscle migrates below the electrodes and muscle mechanics change with different sarcomere – distance (besides other biomechanical aspects)</td>
</tr>
<tr>
<td><strong>Range of motion (ROM)</strong></td>
<td>In analogy to the previous factor, a varying range of motion significantly increase the variability of findings and needs an appropriate standardization</td>
</tr>
<tr>
<td><strong>Movement velocity</strong></td>
<td>Any repetition cycle means constant acceleration and braking, higher velocity means increased acceleration and more motor unit recruitment per time, which finally results in varying overall contraction times and innervation levels</td>
</tr>
<tr>
<td><strong>Load or resistance</strong></td>
<td>Without the understanding of a given load condition or the lack of repeatable resistance, it is not possible to perform e.g. test-retest designs or fatigue studies or other EMG test to test comparisons</td>
</tr>
<tr>
<td><strong>Duration/Repetitions</strong></td>
<td>Beyond 30% MVC innervation intensity, the static contraction duration or amount of dynamic repetitions needs to be considered as a strong determining factor of influence (e.g. fatigue)</td>
</tr>
<tr>
<td><strong>Preliminary status</strong></td>
<td>The metabolic and central nervous conditions and also the time of day may be considered as a factor of uncontrolled variability.</td>
</tr>
</tbody>
</table>
Fig. 82: Example of optimal test standardization. All factors except one are kept constant.
Fig. 83: Equal weight distribution by using two scales or a tilting plate.
Fig. 84: Standardized ROM by using mirrors with grid lines
Fig. 85: Standardized ROM, body position and load by machines
Fig. 86: Control of any movement parameter by biofeedback bars and predefined ranges
Fig 87: Different levels of standardization depend on the general test condition.

- Low: Manual Resistance Tests
- Medium: Free Functional Movements
- High: Static Hold + Constant Load
- Very High: Machine Based Tests
<table>
<thead>
<tr>
<th><strong>EMG Triggered to Movement</strong></th>
<th></th>
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<tbody>
<tr>
<td><strong>Test within a reproducible static joint/ position</strong></td>
<td>Simplest and easiest way to determine a movement position - no special marker or trigger routines is needed!</td>
</tr>
<tr>
<td><strong>Add manual marker lines in real-time</strong></td>
<td>While recording, place manual markers in your record to indicate start and end of a movement phase - for slow movements only!</td>
</tr>
<tr>
<td><strong>Use synchronized video imaging to place event markers</strong></td>
<td>Regular or High Speed video can be synchronized to EMG recordings to allow event definition</td>
</tr>
<tr>
<td><strong>Use goniometers, inclinometers or accelerometers on subject or built in machines</strong></td>
<td>Mobile sensors can be attached to the subject and will be recorded together with EMG. Attach goniometers/inclinometers to machine lever arms</td>
</tr>
<tr>
<td><strong>Apply foot switches</strong></td>
<td>Foot switches are mounted below the feet in gait analysis or contact plates are used in jump testing</td>
</tr>
<tr>
<td><strong>Use force plates or contact plates</strong></td>
<td>The ground reaction force signal and contact mats are a very good indicator of ground contact</td>
</tr>
<tr>
<td>Period Definition</td>
<td>Remarks</td>
</tr>
<tr>
<td>-------------------------------------------------------</td>
<td>-------------------------------------------------------------------------</td>
</tr>
<tr>
<td>Whole record</td>
<td>The start and stop of recording is arranged so that the complete record will be calculated as one period</td>
</tr>
<tr>
<td>A single period selection within a record</td>
<td>One period, selected by two markers or a mouse-marked area, will be used as an analysis period. This allows the user to select a certain portion of interest within a record</td>
</tr>
<tr>
<td>One period with a fixed step sequence of sub-phases</td>
<td>Within one selected analysis interval, a sequence of sub-phases starting from the beginning to the end of the interval is used. Typically used in static fatigue tests for the analysis of time domain changes</td>
</tr>
<tr>
<td>Several periods within a record</td>
<td>Within a sequence of markers indicating the beginning and end of an activity, certain periods are selected for analysis. This mode allows, e.g. the comparison of activities recorded within one record</td>
</tr>
<tr>
<td>Several periods with sub-phases</td>
<td>Within each period, two sub-phases such as stance-swing phase in gait or extension-flexion phase in free movements are determined</td>
</tr>
<tr>
<td>Several periods with several sub-phases</td>
<td>Based on two trigger signals, sub-periods are defined: typical application is bilateral gait with left – right foot switches and side comparison</td>
</tr>
</tbody>
</table>
Fig. 88: Easy comparison analysis: two signal portions (e.g. from different tasks) are shown in an over-plot and the differences are analyzed.
Fig. 89: Side comparison within isokinetic testing, based on averaged curves, with healthy and injured (red) side
Fig. 90: Comparison of patients or subjects findings to normative curves, based on time normalized averaged curves.
Comparisons Designs

- **Pre-test versus post-test**: In a treatment, training or any other setup with interventions in between tests.
- **Left Side versus right Side**: Patients: healthy against injured side - analysis based on qualitative level.
- **Activity 1 versus activity 2**: E.g. analysis of exercises and their efficiency - no normalization needed!
- **Test portion 1 versus portion 2**: Time domain changes of parameter e.g. fatigue studies - no normalization needed!
- **Muscle A versus muscle B**: Coordinative aspects in muscle groups.
- **Patient/Subject versus norm curve**: Identification of abnormal patterns.

*Fig. 91: The major comparison designs used within kinesiological EMG studies*
Complete Line of Surface EMG and Sensor Systems

- Multi Channel Cable units
- Wireless LAN Telemetry
- Handheld Biofeedback
- Biomechanical Sensors
Mobile Monitoring Concept and Connectivity

- EMG
- Angle/Inclination
- Force Pressure
- Acceleration
- Foot Switches

Mobile Sensors → Telemetry → Mobile Computing
Real Time Monitoring of Muscle Activity and Performance

Telemetric EMG and other sensor signals

Video synchronized activity

Real Time Analysis